

1. Kuvan neliölevy deformoituu tasossaan siten, että sen vaakasuora sivupari pitenee 2 promillea ja pystysuora sivupari lyhenee promillen. Määritä analyttisesti laskemalla (ei trigonometrisesti) neliön lävistäjien AD ja BC välisen suoran kulman liukuma.

2. Betonikuutiota, jonka särmä $h = 100 \text{ mm}$ ja lujuusluokka K40, puristetaan vaakatasossa olevilla voimilla $F = 90 \text{ kN}$. Laske kuution itseisarvoltaan suurin leikkausjännitys. Paljonko kuution tilavuus muuttuu, kun materiaalikertoimet ovat $E = 32 \text{ GPa}$ ja $\nu = 0,10$?

3. Valuraudan vetomurtolujuus on 280 MPa ja puristusmurtolujuus 420 MPa . Määritä materiaalin varmuus murtumisen suhteen, kun rakenneosan eniten rasitetun pisteen jännitystila on kuvan mukainen. Käytä *MOHR-COULOMB*in murtumishypoteesia.

4. Metalliseoksesta tehty kuvan mukainen säröllinen koekappale murtui kuormittavan voiman arvolla $F = 53,2 \text{ kN}$. Laske materiaalin murtumissitkeys. $L = 200 \text{ mm}$, $b = 50 \text{ mm}$, $h = 100 \text{ mm}$, $a = 53 \text{ mm}$

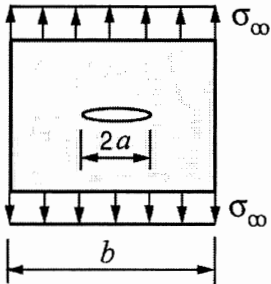
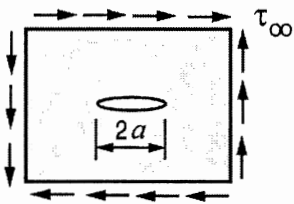
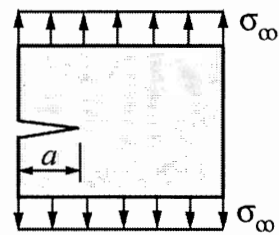
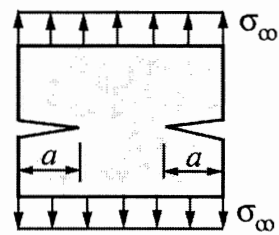
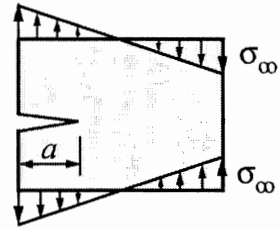
KÄÄNNÄ!

5. Valitse seuraavista vaihtoehdoista se yksi, jota pidät parhaimpana:

- (1) Pääjännitysten on aina oltava positiivisia.
- (2) Maksimileikkausjännitys esiintyy jännityselementin tahkossa, jossa ei ole normaalijännitystä.
- (3) Muodonmuutostilan pääinvariantit riippuvan valitusta koordinaatistosta.
- (4) Teräksen murtumissitkeys pienenee teräksen lujuuden kasvaessa.
- (5) Paksun levyn läpisärön kärjessä vallitsee tasojännitystila.

Oikeasta vastauksesta saa +3 pistettä ja väärästä -1 pisteen. Vastaamattomuudesta saa nollan.

Taulukko 1 Jännitysintensiiteettikertoimia

1		$K_I = \sigma_\infty \sqrt{\pi a} \frac{1 - (a/b) + 1,304 (a/b)^2}{\sqrt{1 - 2a/b}}$ $K_I \approx \sigma_\infty \sqrt{\pi a} \quad , \text{ kun } a/b \ll 1$
2		$K_{II} = \tau_\infty \sqrt{\pi a}$
3		$a/b < 0,7$ $K_I = \sigma_\infty \sqrt{\pi a} (1,12 - 0,23(a/b) + 10,6(a/b)^2 - 21,7(a/b)^3 + 30,4(a/b)^4)$ $K_I \approx 1,12 \sigma_\infty \sqrt{\pi a} \quad , \text{ kun } a/b \ll 1$
4		$K_I = \sigma_\infty \sqrt{\pi a} \frac{1,12 - 1,22(a/b) + 1,04(a/b)^3}{\sqrt{1 - 2a/b}}$ $K_I \approx 1,12 \sigma_\infty \sqrt{\pi a} \quad , \text{ kun } a/b \ll 1$
5		$a/b < 0,7$ $K_I = \sigma_\infty \sqrt{\pi a} (1,12 - 1,39(a/b) + 7,3(a/b)^2 - 13(a/b)^3 + 14(a/b)^4)$ $K_I \approx 1,12 \sigma_\infty \sqrt{\pi a} \quad , \text{ kun } a/b \ll 1$

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KAAVAKOKOELMA

$$\mathbf{t} = \bar{\sigma} + \bar{\tau} \quad \bar{\sigma} = d\mathbf{N}/dA \quad \bar{\tau} = d\mathbf{Q}/dA \quad \{t_\alpha\} = [S] \{n_\alpha\}$$

$$[S] = \begin{bmatrix} \sigma_x & \tau_{xy} & \tau_{xz} \\ \tau_{xy} & \sigma_y & \tau_{yz} \\ \tau_{xz} & \tau_{yz} & \sigma_z \end{bmatrix} \quad \{n\} = \begin{bmatrix} l \\ m \\ n \end{bmatrix} \quad l^2 + m^2 + n^2 = 1 \quad \mathbf{n} = l\mathbf{i} + m\mathbf{j} + n\mathbf{k}$$

$$\tau_{ij} = \tau_{ji} \quad \sigma_\alpha = \mathbf{t}_\alpha \cdot \mathbf{n}_\alpha \quad \bar{\tau}_\alpha = \mathbf{t}_\alpha - \bar{\sigma}_\alpha \quad \sigma_\alpha = \{n_\alpha\}^\top [S] \{n_\alpha\}$$

$$t_{\alpha i} = \sigma_{ij} n_j \quad \bar{t}_\alpha = \sigma_\alpha \mathbf{n}_\alpha \quad \sigma_\alpha = \sigma_{ij} n_i n_j \quad \sigma_{ij} n_j = \sigma_\alpha n_i$$

$$[S] \{n_\alpha\} = \sigma_\alpha \{n_\alpha\} \quad I_1^\sigma = \text{trace}[S] = \sigma_x + \sigma_y + \sigma_z \quad I_3^\sigma = \det[S]$$

$$I_2^\sigma = \begin{vmatrix} \sigma_x & \tau_{xy} \\ \tau_{xy} & \sigma_y \end{vmatrix} + \begin{vmatrix} \sigma_x & \tau_{xz} \\ \tau_{xz} & \sigma_z \end{vmatrix} + \begin{vmatrix} \sigma_y & \tau_{yz} \\ \tau_{yz} & \sigma_z \end{vmatrix} \quad \sigma_\alpha^3 - I_1^\sigma \sigma_\alpha^2 + I_2^\sigma \sigma_\alpha - I_3^\sigma = 0$$

$$I_1^\sigma = \sigma_1 + \sigma_2 + \sigma_3 \quad I_2^\sigma = \sigma_1 \sigma_2 + \sigma_1 \sigma_3 + \sigma_2 \sigma_3 \quad I_3^\sigma = \sigma_1 \sigma_2 \sigma_3$$

$$\sigma_{\hat{x}} = \sigma_x \cos^2 \alpha + \sigma_y \sin^2 \alpha + \tau_{xy} \sin(2\alpha) \quad \tau_{\hat{x}\hat{y}} = -\frac{1}{2}(\sigma_x - \sigma_y) \sin(2\alpha) + \tau_{xy} \cos(2\alpha)$$

$$\sigma_k = \frac{1}{2}(\sigma_x + \sigma_y) \quad R = \sqrt{\frac{1}{4}(\sigma_x - \sigma_y)^2 + \tau_{xy}^2} \quad \sigma_\alpha = \sigma_k \pm R$$

$$\tan(2\bar{\alpha}) = \frac{2\tau_{xy}}{\sigma_x - \sigma_y} \quad \tau_{xy} \sin(2\bar{\alpha}) > 0 \quad \tau_{\max} = \frac{1}{2}(\sigma_I - \sigma_{III})$$

$$\sigma_{\text{okt}} = \frac{1}{3}(\sigma_1 + \sigma_2 + \sigma_3) = \frac{1}{3} I_1^\sigma = \frac{1}{3} \sigma_{kk} \quad \tau_{\text{okt}} = \frac{\sqrt{2}}{3} \sqrt{I_1^2 - 3I_3}$$

$$\tau_{\text{okt}}^2 = \frac{1}{9} [(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2] \quad [S] = [S_p] + [S_D]$$

$$\sigma_k \equiv p = \frac{1}{3}(\sigma_x + \sigma_y + \sigma_z) = \frac{1}{3} I_1^\sigma \quad [S_D] = (s_{ij}) \quad [S_p] = (p \delta_{ij})$$

$$s_{ij} = \sigma_{ij} - p \delta_{ij} \quad s_\alpha = \sigma_\alpha - \sigma_k \quad J_1^\sigma = 0 \quad -J_2^\sigma = \frac{1}{2} s_{ij} s_{ij}$$

$$-J_2^\sigma = \frac{1}{2}(s_1^2 + s_2^2 + s_3^2) \quad -J_2^\sigma = \frac{1}{3}(I_1^2 - 3I_2) \quad \tau_{\text{okt}} = \sqrt{\frac{2}{3}(-J_2^\sigma)}$$

$$J_3^\sigma = \frac{1}{27}(2I_1^3 - 9I_1 I_2 + 27I_3) \quad s_\alpha^3 + J_2^\sigma s_\alpha - J_3^\sigma = 0 \quad s_\alpha = 2\sqrt{-\frac{1}{3} J_2^\sigma} \cos \theta$$

$$\cos(2\theta) = \frac{1}{2} J_3^\sigma (-\frac{1}{3} J_2^\sigma)^{-3/2} \quad \sigma_i = s_i + \sigma_k$$

$$\sigma_{x \rightarrow x} + \tau_{xy \rightarrow y} + \tau_{xz \rightarrow z} + f_x = 0$$

$$\tau_{xy \rightarrow x} + \sigma_{y \rightarrow y} + \tau_{yz \rightarrow z} + f_y = 0 \quad [S] \{n\} = \{t\}, P \in S_\sigma, \{u\} = \{\underline{u}\}, P \in S_u$$

$$\tau_{xz \rightarrow x} + \tau_{yz \rightarrow y} + \sigma_{z \rightarrow z} + f_z = 0$$

$$\mathbf{u}(\mathbf{P}) = \mathbf{r}(\mathbf{P}) - \mathbf{r}(\hat{\mathbf{P}}) \quad \mathbf{u} = u\mathbf{i} + v\mathbf{j} + w\mathbf{k} \quad u = \hat{x} - x, \quad v = \hat{y} - y, \quad w = \hat{z} - z$$

$$\hat{x} = \hat{x}(x, y, z), \quad \hat{y} = \hat{y}(x, y, z), \quad \hat{z} = \hat{z}(x, y, z) \quad d\mathbf{u} = du\mathbf{i} + dv\mathbf{j} + dw\mathbf{k}$$

$$\mathbf{u}(\mathbf{r} + d\mathbf{r}) = \mathbf{u}(\mathbf{r}) + d\mathbf{u} \quad \mathbf{r} = x\mathbf{i} + y\mathbf{j} + z\mathbf{k} \quad d\mathbf{r} = dx\mathbf{i} + dy\mathbf{j} + dz\mathbf{k}$$

$$\{d\mathbf{u}\} = [D]\{d\mathbf{r}\} \quad [D] = \begin{bmatrix} \partial u/\partial x & \partial u/\partial y & \partial u/\partial z \\ \partial v/\partial x & \partial v/\partial y & \partial v/\partial z \\ \partial w/\partial x & \partial w/\partial y & \partial w/\partial z \end{bmatrix}$$

$$(1 + \varepsilon)^2 = 1 + 2\{e\}^T [D]\{e\} + ([D]\{e\})^2 \quad \tilde{\varepsilon} = \{e\}^T [D]\{e\}$$

$$[D] = [V] + [\Omega] \quad \tilde{\varepsilon} = \{e\}^T [V]\{e\} \quad \{e\}^T [\Omega]\{e\} = 0$$

$$[V] = \begin{bmatrix} \varepsilon_x & \varepsilon_{xy} & \varepsilon_{xz} \\ \varepsilon_{xy} & \varepsilon_y & \varepsilon_{yz} \\ \varepsilon_{xz} & \varepsilon_{yz} & \varepsilon_z \end{bmatrix} \quad [\Omega] = \begin{bmatrix} 0 & -\varphi_z & \varphi_y \\ \varphi_z & 0 & -\varphi_x \\ -\varphi_y & \varphi_x & 0 \end{bmatrix}$$

$$\varepsilon_x = \partial u/\partial x \quad \varepsilon_y = \partial v/\partial y \quad \varepsilon_z = \partial w/\partial z \quad \gamma_{xy} = \partial u/\partial y + \partial v/\partial x$$

$$\gamma_{yz} = \partial v/\partial z + \partial w/\partial y \quad \gamma_{xz} = \partial u/\partial z + \partial w/\partial x$$

$$\gamma_{xy} = 2\varepsilon_{xy} \quad \gamma_{yz} = 2\varepsilon_{yz} \quad \gamma_{xz} = 2\varepsilon_{xz} \quad \sin\phi = \frac{|\mathbf{e} \times \mathbf{D}\mathbf{e}|}{1 + \varepsilon}$$

$$\phi \approx |\mathbf{e} \times \mathbf{D}\mathbf{e}| \quad \varepsilon_{x,yy} + \varepsilon_{y,xx} = 2\varepsilon_{xy,xy} \quad \{d\hat{\mathbf{r}}\} = [F]\{d\mathbf{r}\}$$

$$F_{ij} = \partial \hat{x}_i / \partial x_j \quad J = \det[F] \quad d\hat{V} = J dV \quad \mathcal{E} = J^{-1} \quad \mathcal{E} = \Delta(dV)/dV$$

$$\rho = J \hat{\rho} \quad [V]\{e_{\bar{\alpha}}\} = \varepsilon_{\bar{\alpha}} \{e_{\bar{\alpha}}\} \quad \mathcal{E} = I_1^\varepsilon + I_2^\varepsilon + I_3^\varepsilon \approx I_1^\varepsilon$$

$$\varepsilon_{\bar{x}} = \varepsilon_x \cos^2 \alpha + \varepsilon_y \sin^2 \alpha + \varepsilon_{xy} \sin(2\alpha) \quad \{\sigma\} = [E]\{\varepsilon\}$$

$$\varepsilon_{\bar{x}\bar{y}} = -\frac{1}{2}(\varepsilon_x - \varepsilon_y) \sin(2\alpha) + \varepsilon_{xy} \cos(2\alpha) \quad \sigma_{ij} = \lambda \varepsilon_{kk} \delta_{ij} + 2\mu \varepsilon_{ij}$$

$$[E] = \frac{E}{(1+\nu)((1-2\nu))} \begin{bmatrix} 1-\nu & \nu & \nu & 0 & 0 & 0 \\ \nu & 1-\nu & \nu & 0 & 0 & 0 \\ \nu & \nu & 1-\nu & 0 & 0 & 0 \\ 0 & 0 & 0 & \bar{\nu} & 0 & 0 \\ 0 & 0 & 0 & 0 & \bar{\nu} & 0 \\ 0 & 0 & 0 & 0 & 0 & \bar{\nu} \end{bmatrix} \quad \bar{\nu} = \frac{1}{2}(1-2\nu)$$

$$G = \frac{E}{2(1+\nu)} \quad \lambda = \frac{\nu E}{(1+\nu)(1-2\nu)} \quad \mu = G = \frac{E}{2(1+\nu)} \quad E = \frac{\mu(2\mu+3\lambda)}{\mu+\lambda}$$

$$\nu = \frac{\lambda}{2(\mu+\lambda)} \quad K = \frac{E}{3(1-2\nu)} \quad \sigma_k = K \mathcal{E} = 3K \varepsilon_k \quad K = \lambda + \frac{2}{3}\mu$$

$$[S_p] = 3K[V_p] \quad [S_D] = 2G[V_D]$$

$$\varepsilon = \varepsilon^e + \varepsilon^p \quad d\sigma = E_t d\varepsilon \quad d\sigma = E_p \varepsilon^p \quad \frac{1}{E_t} = \frac{1}{E} + \frac{1}{E_p}$$

$$\kappa \equiv W_p = \int \sigma d\varepsilon^p \quad \kappa \equiv \varepsilon_p = \int \sqrt{d\varepsilon^p d\varepsilon^p}$$

$$\max \{ |\sigma_2 - \sigma_3|, |\sigma_3 - \sigma_1|, |\sigma_1 - \sigma_2| \} = R_e \quad (\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2 = 2 R_e^2$$

$$\tau_{\max} = \frac{1}{2} (\sigma_I - \sigma_{III}) \quad \bar{\sigma} = \frac{1}{2} (\sigma_I + \sigma_{III}) \quad R_{-e} = \frac{2 \bar{\sigma} \cos \varphi}{1 - \sin \varphi} \quad R_e = \frac{2 \bar{\sigma} \cos \varphi}{1 + \sin \varphi}$$

$$m = \frac{R_{-e}}{R_e} = \frac{1 + \sin \varphi}{1 - \sin \varphi} \quad m \sigma_i - \sigma_j = R_{-e} \quad , \quad \sigma_i \geq \sigma_k \geq \sigma_j \quad , \quad i, j, k = 1, 2, 3$$

$$\sqrt{-J_2} - k = 0 \quad \alpha I_1 + \sqrt{-J_2} - k = 0 \quad k = \frac{2}{\sqrt{3}} \frac{R_{-e}}{m+1}$$

$$(1 - 3 \alpha^2) (\sigma_1^2 + \sigma_2^2) - (1 + 6 \alpha^2) \sigma_1 \sigma_2 + 6 k \alpha (\sigma_1 + \sigma_2) = 3 k^2 \quad \alpha = \frac{1}{\sqrt{3}} \frac{m-1}{m+1}$$

Suorakulmio: $M_m = \frac{1}{6} b h^2 R_e \quad M_p = \frac{1}{4} b h^2 R_e \quad \Phi = M_p / M_m$

$$M_p = R_e (\bar{S}_1 + |\bar{S}_2|) \quad v_{,xx} = -\frac{2 R_e / E h}{\sqrt{3} \sqrt{1 - |M| / M_p}} \operatorname{sgn}(M)$$

$$\sigma_x = \frac{K_I}{\sqrt{2 \pi r}} \cos(\frac{1}{2} \theta) (1 - \sin(\frac{1}{2} \theta) \sin(\frac{1}{2} \theta)) \quad \tau_{xy} = \frac{K_I}{\sqrt{2 \pi r}} \cos(\frac{1}{2} \theta) \sin(\frac{1}{2} \theta) \cos(\frac{1}{2} \theta)$$

$$\sigma_y = \frac{K_I}{\sqrt{2 \pi r}} \cos(\frac{1}{2} \theta) (1 + \sin(\frac{1}{2} \theta) \sin(\frac{1}{2} \theta)) \quad K_I = \lim_{r \rightarrow 0} (\sigma_y(r, 0) \sqrt{2 \pi r})$$

$$\sigma_f = \frac{K_I}{\sqrt{\pi a}} \quad a_t = \frac{1}{\pi} \left(\frac{K_{Ic}}{R_e} \right)^2 \quad r_p = \frac{1}{2 \pi} \left(\frac{K_I}{R_e} \right)^2$$

$$\frac{da}{dN} = C (\Delta K_I)^n \quad \frac{da}{dN} = C (\eta \sigma_a \sqrt{\pi a})^n$$

$$\sigma = E \varepsilon \quad \sigma = \eta \varepsilon^\bullet \quad \text{MAXWELL: } \varepsilon^\bullet = \frac{\sigma^\bullet}{E} + \frac{\sigma}{\eta} \quad , \quad \text{KELVIN-VOIGT: } \varepsilon^\bullet + \frac{E}{\eta} \varepsilon = \frac{\sigma}{\eta}$$

Standardimalli: $\varepsilon^\bullet + \frac{E_2}{\eta} \varepsilon = \frac{\sigma}{\eta} (1 + \frac{E_2}{E_1}) + \frac{\sigma^\bullet}{E_1}$ (solidi)